



درس ۱۹

طراحی فیلترهای IIR گسسته–زمان از روی فیلترهای ییوسته-زمان

Discrete-Time IIR Filter Design from Continuous-Time Filters

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Discrete-Time IIR Filter Design from Continuous-Time Filters

Digital Signal Processing

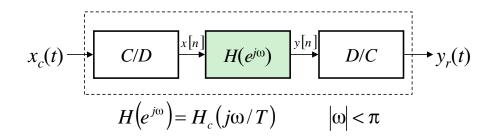
Filter Design Techniques

- Filter: Any discrete-time system that modifies certain frequencies
- Frequency-selective filters pass only certain frequencies

- Filter Design Steps
 - Specification
 - Problem or application specific
 - Approximation of specification with a discrete-time system
 - Our focus is to go from spec to discrete-time system
 - Implementation
 - Realization of discrete-time systems depends on target technology

Filter Design Techniques

- We already studied the use of discrete-time systems to implement a continuous-time system
 - If our specifications are given in continuous time we can use:



Filter Specifications

• Specifications

- Passband

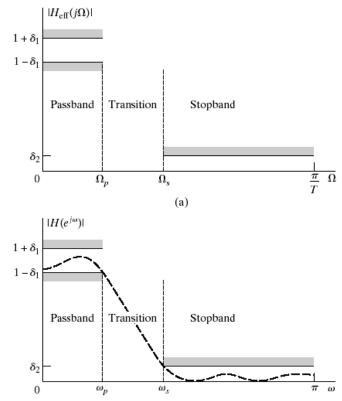
 $0.99 \le |H_{eff}(j\Omega)| = 1.01 \quad 0 \le \Omega \le 2\pi (2000)$

- Stopband $\left|H_{eff}(j\Omega)\right| \le 0.001 \quad 2\pi(3000) \le \Omega$

• Parameters

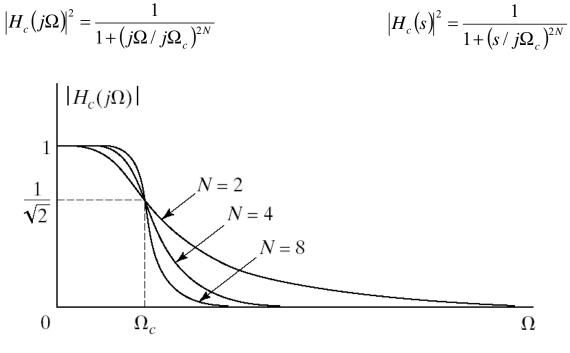
 $\delta_1 = 0.01$ $\delta_2 = 0.001$ $\Omega_p = 2\pi (2000)$ $\Omega_s = 2\pi (3000)$

- Specs in dB
 - Ideal passband gain $=20\log(1) = 0 \text{ dB}$
 - Max passband gain = $20\log(1.01) = 0.086$ dB
 - Max stopband gain = $20\log(0.001) = -60 \text{ dB}$



Butterworth Lowpass Filters

- **Passband** is designed to be maximally flat
- The magnitude-squared function is of the form



Poles: $s_k = (-1)^{1/2N} (j\Omega_c) = \Omega_c e^{(j\pi/2N)(2k+N-1)}$ for k = 0, 1, ..., 2N-1

Chebyshev Filters

- Equiripple in the passband and monotonic in the stopband (Type I)
- Or equiripple in the stopband and monotonic in the passband (Type II)

Type I:
$$|H_c(j\Omega)|^2 = \frac{1}{1 + \varepsilon^2 V_N^2(\Omega / \Omega_c)}$$
 $V_N(x) = \cos(N \cos^{-1} x)$
 $1 - \epsilon$
 $\int_{\Omega_c} \frac{|H_c(j\Omega)|}{\Omega_c}$
Type II: $|H_c(j\Omega)|^2 = \frac{1}{1 + (\varepsilon^2 V_N^2(\Omega / \Omega_c))^{-1}}$ $V_N(x) = \cos(N \cos^{-1} x)$

Filter Design by Impulse Invariance

- Remember impulse invariance
 - Mapping a continuous-time impulse response to discrete-time
 - Mapping a continuous-time frequency response to discrete-time

$$h[n] = T_d h_c(nT_d)$$
$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} H_c\left(j\frac{\omega}{T_d} + j\frac{2\pi}{T_d}k\right)$$

• If the continuous-time filter is bandlimited to

$$H_{c}(j\Omega) = 0 \qquad |\Omega| \ge \pi / T_{d}$$
$$H(e^{j\omega}) = H_{c}\left(j\frac{\omega}{T_{d}}\right) \quad |\omega| \le \pi$$

- If we start from discrete-time specifications T_d cancels out
 - Start with discrete-time spec in terms of $\boldsymbol{\omega}$
 - Go to continuous-time $\Omega = \omega / T$ and design continuous-time filter
 - Use impulse invariance to map it back to discrete-time $\omega = \Omega T$
- Works best for **bandlimited filters** due to possible aliasing

Impulse Invariance of System Functions

- Develop impulse invariance relation between system functions (disc. vs. cont.)
- Partial fraction expansion of transfer function

$$H_c(s) = \sum_{k=1}^{N} \frac{A_k}{s - s_k}$$

• Corresponding impulse response

$$h_c(t) = \begin{cases} \sum_{k=1}^N A_k e^{s_k t} & t \ge 0\\ 0 & t < 0 \end{cases}$$

• Impulse response of discrete-time filter

$$h[n] = T_d h_c(nT_d) = \sum_{k=1}^N T_d A_k e^{s_k nT_d} u[n] = \sum_{k=1}^N T_d A_k (e^{s_k T_d})^n u[n]$$

• System function

$$H(z) = \sum_{k=1}^{N} \frac{T_d A_k}{1 - e^{s_k T_d} z^{-1}}$$

• Pole $s = s_k$ in *s*-domain transform into pole at $e^{s_k T_d}$

Example

• Impulse invariance applied to Butterworth

$$0.89125 \le \left| H\left(e^{j\omega}\right) \right| \le 1 \qquad 0 \le \left| \omega \right| \le 0.2\pi$$
$$\left| H\left(e^{j\omega}\right) \right| \le 0.17783 \qquad 0.3\pi \le \left| \omega \right| \le \pi$$

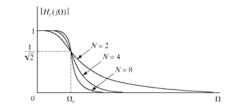
- Since sampling rate T_d cancels out we can assume $T_d = 1$
- Map spec to continuous time

$$T_d = 1 \implies \Omega = \omega / T_d = \omega$$
$$0.89125 \le |H(j\Omega)| \le 1 \qquad 0 \le |\Omega| \le 0.2\pi$$
$$|H(j\Omega)| \le 0.17783 \qquad 0.3\pi \le |\Omega| \le \pi$$

• Butterworth filter is monotonic so spec will be satisfied if

 $|H_c(j0.2\pi)| \ge 0.89125$ and $|H_c(j0.3\pi)| \le 0.17783$

$$\left|H_{c}(j\Omega)\right|^{2} = \frac{1}{1 + (j\Omega / j\Omega_{c})^{2N}}$$



• Determine *N* and Ω_c to satisfy these conditions

Example Cont'd

• Satisfy both constrains

$$1 + \left(\frac{0.2\pi}{\Omega_c}\right)^{2N} = \left(\frac{1}{0.89125}\right)^2 \quad \text{and} \quad 1 + \left(\frac{0.3\pi}{\Omega_c}\right)^{2N} = \left(\frac{1}{0.17783}\right)^2$$

• Solve these equations to get

 $N = 5.8858 \cong 6$ and $\Omega_c = 0.70474$

- *N* must be an integer so we round it up to meet the spec
- Poles of transfer function

$$s_k = (-1)^{1/12} (j\Omega_c) = \Omega_c e^{(j\pi/12)(2k+11)}$$
 for $k = 0, 1, ..., 11$

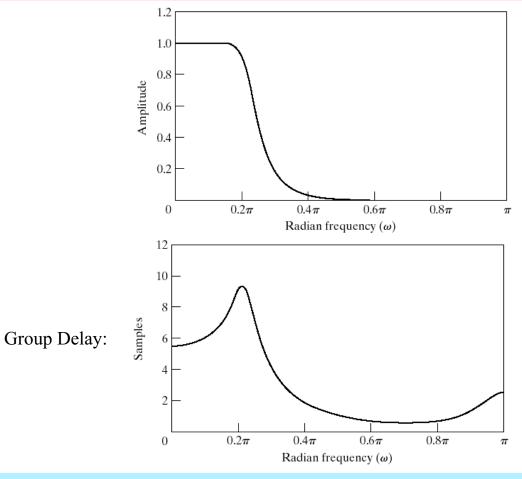
• The transfer function

$$H(s) = \frac{0.12093}{(s^2 + 0.364s + 0.4945)(s^2 + 0.9945s + 0.4945)(s^2 + 1.3585s + 0.4945)}$$

• Mapping to z-domain $H(z) = \frac{0.2871 - 0.4466z^{-1}}{1 - 1.2971z^{-1} + 0.6949z^{-2}} + \frac{-2.1428 + 1.1455z^{-1}}{1 - 1.0691z^{-1} + 0.3699z^{-2}} + \frac{1.8557 - 0.6303z^{-1}}{1 - 0.9972z^{-1} + 0.257z^{-2}}$

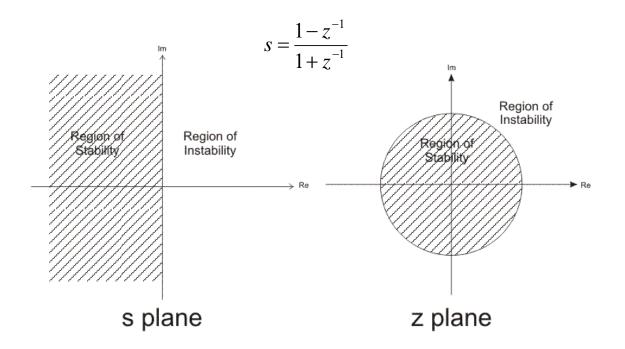
Digital Signal Processing

Example Cont'd



Digital Signal Processing

Bilinear Transformation



Filter Design by Bilinear Transformation

- Get around the **aliasing problem** of impulse invariance
- Map the entire s-plane onto the unit-circle in the z-plane
 - Nonlinear transformation
 - Frequency response subject to warping
- Bilinear transformation

$$s = \frac{2}{T_d} \left(\frac{1 - z^{-1}}{1 + z^{-1}} \right)$$

• Transformed system function

$$H(z) = H_{c}\left[\frac{2}{T_{d}}\left(\frac{1-z^{-1}}{1+z^{-1}}\right)\right]$$

- Again T_d cancels out so we can ignore it
- We can solve the transformation for z as

$$z = \frac{1 + (T_d / 2)s}{1 - (T_d / 2)s} = \frac{1 + \sigma T_d / 2 + j\Omega T_d / 2}{1 - \sigma T_d / 2 - j\Omega T_d / 2} \qquad s = \sigma + j\Omega$$

- Maps the left-half s-plane into the inside of the unit-circle in z
 - Stable in one domain would stay in the other

Bilinear Transformation

• On the unit circle the transform becomes

$$z = \frac{1 + j\Omega T_d / 2}{1 - j\Omega T_d / 2} = e^{j\omega}$$

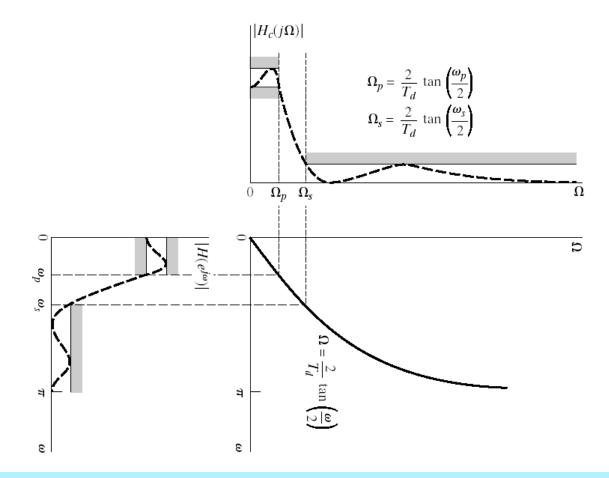
• To derive the relation between ω and Ω

$$s = \frac{2}{T_d} \left(\frac{1 - e^{-j\omega}}{1 + e^{-j\omega}} \right) = \sigma + j\Omega = \frac{2}{T_d} \left[\frac{2e^{-j\omega/2}j\sin(\omega/2)}{2e^{-j\omega/2}\cos(\omega/2)} \right] = \frac{2j}{T_d} \tan\left(\frac{\omega}{2}\right)$$

• Which yields

$$\Omega = \frac{2}{T_d} \tan\left(\frac{\omega}{2}\right) \quad \text{or} \quad \omega = 2 \arctan\left(\frac{\Omega T_d}{2}\right)$$

Bilinear Transformation



Example

- Bilinear transform applied to Butterworth $0.89125 \le |H(e^{j\omega})| \le 1$ $0 \le |\omega| \le 0.2\pi$ $|H(e^{j\omega})| \le 0.17783$ $0.3\pi \le |\omega| \le \pi$
- Apply bilinear transformation to specifications

$$0.89125 \le |H(j\Omega)| \le 1 \qquad 0 \le |\Omega| \le \frac{2}{T_d} \tan\left(\frac{0.2\pi}{2}\right)$$
$$|H(j\Omega)| \le 0.17783 \quad \frac{2}{T_d} \tan\left(\frac{0.3\pi}{2}\right) \le |\Omega| < \infty$$

• We can assume $T_d = 1$ and apply the specifications to

$$\left|H_{c}(j\Omega)\right|^{2} = \frac{1}{1 + \left(\Omega / \Omega_{c}\right)^{2N}}$$

• To get

$$1 + \left(\frac{2\tan 0.1\pi}{\Omega_c}\right)^{2N} = \left(\frac{1}{0.89125}\right)^2 \text{ and } 1 + \left(\frac{2\tan 0.15\pi}{\Omega_c}\right)^{2N} = \left(\frac{1}{0.17783}\right)^2$$

• Solve *N* and Ω_c

$$N = \frac{\log\left[\left(\left(\frac{1}{0.17783}\right)^2 - 1\right) / \left(\left(\frac{1}{0.89125}\right)^2 - 1\right)\right]}{2\log[\tan(0.15\pi)/\tan(0.1\pi)]} = 5.305 \cong 6 \qquad \Omega_c = 0.766$$

• The resulting transfer function has the following poles

$$s_k = (-1)^{1/12} (j\Omega_c) = \Omega_c e^{(j\pi/12)(2k+11)}$$
 for $k = 0, 1, ..., 11$

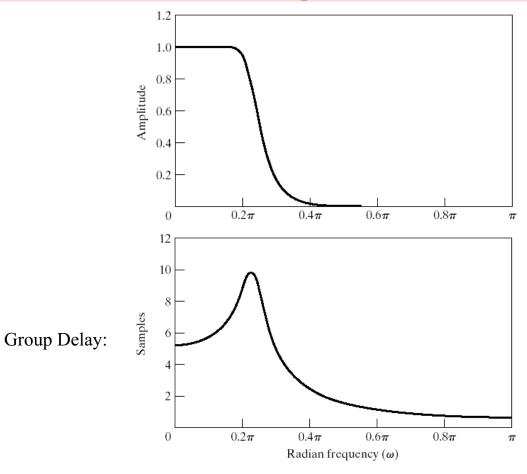
• Resulting in

$$H_{c}(s) = \frac{0.20238}{(s^{2} + 0.3996s + 0.5871)(s^{2} + 1.0836s + 0.5871)(s^{2} + 1.4802s + 0.5871)}$$

• Applying the bilinear transform yields

$$H(z) = \frac{0.0007378(1+z^{-1})^{6}}{(1-1.2686z^{-1}+0.7051z^{-2})(1-1.0106z^{-1}+0.3583z^{-2})} \times \frac{1}{(1-0.9044z^{-1}+0.2155z^{-2})}$$

Example Cont'd



Digital Signal Processing