





درس ۱

معرفی درس

Course Introduction

کاظم فولادی دانشکده مهندسـی برق و کامپیوتر دانشگاه تهران

http://courses.fouladi.ir/dsp

Digital Signal Processing (DSP)

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Course Details

- Objective
 - Establish a background in Digital Signal Processing Theory
- Required Text
 - Discrete-Time Signal Processing,
 - Prentice Hall, 3rd Edition
 - Alan Oppenheim, Ronald Schafer, John Buck

Sound applications

- Compression, enhancement, special effects, synthesis, recognition, echo cancellation,...
- Cell Phones, MP3 Players, Movies, Dictation, Text-to-speech,...
- Communication
 - Modulation, coding, detection, equalization, echo cancellation,...
 - Cell Phones, dial-up modem, DSL modem, Satellite Receiver,...
- Automotive
 - ABS, GPS, Active Noise Cancellation, Cruise Control, Parking,...
- Medical
 - Magnetic Resonance, Tomography, Electrocardiogram,...
- Military
 - Radar, Sonar, Space photographs, remote sensing,...
- Image and Video Applications
 - DVD, JPEG, Movie special effects, video conferencing,...
- Mechanical
 - Motor control, process control, oil and mineral prospecting,...

- Introduction to Digital Signal Processing
- Discrete-Time Signals and System
 - Discrete-Time Signals: Sequences (2.1)
 - Discrete-Time Systems (2.2)
 - Linear Time-Invariant Systems (2.3)
 - Properties of Linear Time-Invariant Systems (2.4)
 - Linear Constant-Coefficient Difference Equations (2.5)
 - Frequency-Domain Representation of Discrete-Time Signals (2.6)
 - Representation of Sequences by Fourier Transforms (2.7)
 - Symmetry Properties of the Fourier Transform (2.8)
 - Fourier Transform Theorems (2.9)

• The z-Transform

- z-Transform (3.1)
- Properties of the Region of Convergence (ROC) of the z-Transform (3.2)
- The Inverse z-Transform (3.3)
- z-Transform Properties (3.4)

- Sampling of Continuous-Time Signals
 - Periodic (Uniform) Sampling (4.1)
 - Frequency-Domain Representation of Sampling (4.2)
 - Reconstruction of a Bandlimited Signal from Its Samples (4.3)
 - Discrete-Time Processing of Continuous-Time Signals (4.4)
 - Continuous-Time Processing of Discrete-Time Signals (4.6)
 - Changing the Sampling Rate Using Discrete-Time Processing (4.6)
 - Digital Processing of Analog Signals (4.8)
- Transform Analysis of Linear Time-Invariant Systems
 - The Frequency Response of LTI Systems (5.1)
 - System Functions: Linear Constant-Coefficient Difference Equations (5.2)
 - Frequency Response for Rational System Functions (5.3)
 - Relationship between Magnitude and Phase (5.4)
 - All-Pass Systems (5.5)
 - Minimum-Phase Systems (5.6)
 - Linear Systems with Generalized Linear Phase (5.7)

Structures for Discrete-Time Systems

- Block Diagram Representation (6.1)
- Signal Flow Graph Representation (6.2)
- Basic Structures for IIR Systems (6.3)
- Transposed Forms (6.4)
- Basic Structures for FIR Systems (6.5)
- Finite Precision Numerical Effects (6.7)
- Effects of Coefficient Quantization (6.8)
- Effects of Round-Off Noise in Digital Filters (6.9)

Filter Design Techniques

- Filter Specifications (7.1)
- Design of Discrete-Time IIR Filters from Continuous-Time Filters (7.2)
- Discrete-Time Butterworth, Chebyshev and Elliptic Filters (7.3)
- Frequency Transformations of Lowpass IIR Filters (7.4)
- Design of FIR Filters by Windowing (7.5)
- Optimum Approximations of FIR Filters (7.7)

The Discrete-Fourier Transform

- Representation of Periodic Sequences: The Discrete Fourier Series (8.1)
- Properties of the Discrete Fourier Series (8.2)
- The Fourier Transform of Periodic Signals (8.3)
- Sampling the Fourier Transform (8.4)
- The Discrete Fourier Transform (8.5)
- Properties of the DFT (8.6)
- Computation of the Discrete-Fourier Transform
 - Fast Fourier Transform Algorithm (9)
- Fourier Analysis of Signals Using the Discrete Fourier Transform (10)
- Parametric Signal Modeling (11)
- Discrete Hilbert Transform (12) *
- Cepstrum Analysis and Homomorphic Deconvolution (13) *
- Applications * (Audio DSP, Image DSP, Video DSP, ...)
- Advanced Topics in DSP *
 - Multi-Rate DSP, Linear Prediction, Power Spectrum Estimation, ...

Signal Processing

- Humans are the most advanced signal processors
 - speech and pattern recognition, speech synthesis,...
- We encounter many types of signals in various applications
 - Electrical signals: voltage, current, magnetic and electric fields,...
 - Mechanical signals: velocity, force, displacement,...
 - Acoustic signals: sound, vibration,...
 - Other signals: pressure, temperature,...
- Most real-world signals are **analog**
 - They are continuous in time and amplitude
 - Convert to voltage or currents using sensors and transducers
- Analog circuits process these signals using
 - Resistors, Capacitors, Inductors, Amplifiers,...
- Analog signal processing examples
 - Audio processing in FM radios
 - Video processing in traditional TV sets

Limitations of Analog Signal Processing

• Accuracy limitations due to

- Component tolerances
- Undesired nonlinearities

• Limited repeatability due to

- Tolerances
- Changes in environmental conditions
 - Temperature
 - Vibration
- Sensitivity to electrical noise
- Limited dynamic range for voltage and currents
- Inflexibility to changes
- Difficulty of implementing certain operations
 - Nonlinear operations
 - Time-varying operations
- Difficulty of storing information

Digital Signal Processing

- Represent signals by a sequence of numbers
 - Sampling or analog-to-digital conversions
- Perform processing on these numbers with a digital processor
 - Digital signal processing
- Reconstruct analog signal from processed numbers
 - Reconstruction or digital-to-analog conversion



- Analog input analog output
 - Digital recording of music
- Analog input digital output
 - Touch tone phone dialing
- Digital input analog output
 - Text to speech
- Digital input digital output
 - Compression of a file on computer

Pros and Cons of Digital Signal Processing

• Pros

- Accuracy can be controlled by choosing word length
- Repeatable
- Sensitivity to electrical noise is minimal
- Dynamic range can be controlled using floating point numbers
- Flexibility can be achieved with software implementations
- Non-linear and time-varying operations are easier to implement
- Digital storage is cheap
- Digital information can be encrypted for security
- Price/performance and reduced time-to-market
- Cons
 - Sampling causes loss of information
 - A/D and D/A requires mixed-signal hardware
 - Limited speed of processors
 - Quantization and round-off errors