



بردازش سیگنال دیجیتال

درس ۱۵

رابطهی میان اندازه و فاز

Relationship between Magnitude and Phase

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Relationship between Magnitude and Phase

Digital Signal Processing

Relation between Magnitude and Phase

• For general LTI system

- Knowledge about magnitude doesn't provide any information about phase
- Knowledge about phase doesn't provide any information about magnitude
- For linear constant-coefficient difference equations however
 - There is some constraint between magnitude and phase
 - If magnitude and number of pole-zeros are known
 - Only a finite number of choices for phase
 - If phase and number of pole-zeros are known
 - Only a finite number of choices for magnitude (ignoring scale)
- A class of systems called minimum-phase
 - Magnitude specifies phase uniquely
 - Phase specifies magnitude uniquely

Square Magnitude System Function

• Explore possible choices of system function of the form

$$\left|H\left(e^{j\omega}\right)^{2} = H\left(e^{j\omega}\right)^{*}H\left(e^{j\omega}\right) = H^{*}\left(1/z^{*}\right)H\left(z\right)|_{z=e^{j\omega}}$$

• Restricting the system to be rational

$$H(z) = \left(\frac{b_0}{a_0}\right) \frac{\prod_{k=1}^{M} (1 - c_k z^{-1})}{\prod_{k=1}^{N} (1 - d_k z^{-1})}$$

$$H^{*}(1/z^{*}) = \left(\frac{b_{0}}{a_{0}}\right) \frac{\prod_{k=1}^{M} (1-c_{k}^{*}z)}{\prod_{k=1}^{N} (1-d_{k}^{*}z)}$$

• The square system function

system function

$$C(z) = H(z)H^{*}(1/z^{*}) = \left(\frac{b_{0}}{a_{0}}\right)^{2} \frac{\prod_{k=1}^{M} (1 - c_{k}z^{-1})(1 - c_{k}^{*}z)}{\prod_{k=1}^{N} (1 - d_{k}z^{-1})(1 - d_{k}^{*}z)}$$

- Given $|H(e^{j\omega})|^2$ we can get C(z)
- What information on H(z) can we get from C(z)?

Poles and Zeros of Magnitude Square System Function

$$C(z) = H(z)H^{*}(1/z^{*}) = \left(\frac{b_{0}}{a_{0}}\right)^{2} \frac{\prod_{k=1}^{M} (1-c_{k}z^{-1})(1-c_{k}^{*}z)}{\prod_{k=1}^{N} (1-d_{k}z^{-1})(1-d_{k}^{*}z)}$$

- For every pole d_k in H(z) there is a pole of C(z) at d_k and $(1/d_k)^*$
- For every zero c_k in H(z) there is a zero of C(z) at c_k and $(1/c_k)^*$
- Poles and zeros of C(z) occur in conjugate reciprocal pairs
- If one of the pole/zero is inside the unit circle the reciprocal will be outside

 Unless there are both on the unit circle
- If H(z) is stable all poles have to be inside the unit circle
 - We can infer which poles of C(z) belong to H(z)
- However, zeros cannot be uniquely determined
 - Example to follow

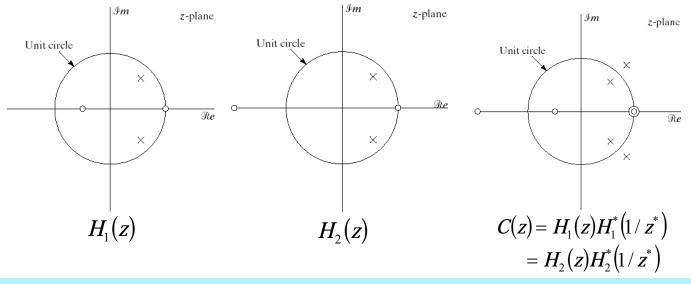
Example

$$H_{1}(z) = \frac{2(1-z^{-1})(1-0.5z^{-1})}{(1-0.8e^{j\pi/4}z^{-1})(1-0.8e^{-j\pi/4}z^{-1})}$$

• Two systems with

$$H_{2}(z) = \frac{(1-z^{-1})(1-2z^{-1})}{(1-0.8e^{j\pi/4}z^{-1})(1-0.8e^{-j\pi/4}z^{-1})}$$

• Both share the same magnitude square system function



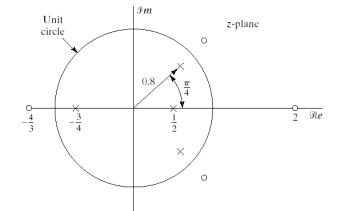
All-Pass System

- A system with <u>frequency response magnitude constant</u>
- Important uses such as compensating for phase distortion
- Simple all-pass system

$$H_{ap}(z) = \frac{z^{-1} - a^*}{1 - az^{-1}}$$

• Magnitude response constant

$$H_{ap}(e^{j\omega}) = \frac{e^{-j\omega} - a^*}{1 - ae^{-j\omega}} = e^{-j\omega} \frac{1 - a^* e^{j\omega}}{1 - ae^{-j\omega}}$$



• Most general form with real impulse response

$$H_{ap}(z) = A \prod_{k=1}^{M_r} rac{z^{-1} - d_k}{1 - d_k z^{-1}} \prod_{k=1}^{M_c} rac{(z^{-1} - c_k^*)(z^{-1} - c_k)}{(1 - c_k z^{-1})(1 - c_k^* z^{-1})}$$

• A: positive constant, d_k : real poles, c_k : complex poles

Phase of All-Pass Systems

$$H_{ap}(e^{j\omega}) = \frac{e^{-j\omega} - a^*}{1 - ae^{-j\omega}} = e^{-j\omega} \frac{1 - a^* e^{j\omega}}{1 - ae^{-j\omega}}$$

• Let's write the phase with *a* represented in polar form

$$\geq \left[\frac{e^{-j\omega} - re^{-j\theta}}{1 - re^{j\theta}e^{-j\omega}}\right] = -\omega - 2\arctan\left[\frac{r\sin(\omega - \theta)}{1 - r\cos(\omega - \theta)}\right]$$

• The group delay of this system can be written as

$$\operatorname{grd}\left[\frac{e^{-j\omega} - re^{-j\theta}}{1 - re^{j\theta}e^{-j\omega}}\right] = \frac{1 - r^2}{1 - 2r\cos(\omega - \theta) + r^2} = \frac{1 - r^2}{\left|1 - re^{j\theta}e^{-j\omega}\right|^2}$$

- For stable and causal system $|\mathbf{r}| < 1$
 - Group delay of all-pass systems is always positive
- Phase between 0 and π is always negative

$$\arg \left[H_{ap}(e^{j\omega}) \right] \le 0 \text{ for } 0 \le \omega < \pi$$