





درس ۷



The z-Transform

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The z-Transform

- Counterpart of the Laplace transform for discrete-time signals
- Generalization of the Fourier Transform
 - Fourier Transform does not exist for all signals
- The z-Transform is often time more convenient to use
- Definition:

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

• Compare to DTFT definition:

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

- *z* is a complex variable that can be represented as $z = r e^{j\omega}$
- Substituting $z = e^{j\omega}$ will reduce the z-transform to DTFT

The z-transform and the DTFT

- The z-transform is a function of the complex z variable
- Convenient to describe on the complex z-plane
- If we plot $z = e^{j\omega}$ for $\omega = 0$ to 2π we get the unit circle



Convergence of the z-Transform

• DTFT does not always converge

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

- Infinite sum not always finite if x[n] no absolute summable
- Example: $x[n] = a^n u[n]$ for |a| > 1 does not have a DTFT
- Complex variable z can be written as $ne^{j\omega}$ so the z-transform

$$X(re^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] (re^{-j\omega})^{-n} = \sum_{n=-\infty}^{\infty} (x[n]r^{-n})e^{-j\omega n}$$

DTFT of x[n] multiplied with exponential sequence rⁿ
For certain choices of r the sum maybe made finite

$$\sum_{n=-\infty}^{\infty} \left| x[n] r^{-n} \right| < \infty$$

Region of Convergence

- The set of values of *z* for which the z-transform converges
- Each value of *r* represents a circle of radius *r*
- The region of convergence is made of circles



- Example: z-transform converges for values of 0.5 < r < 2
 - ROC is shown on the left
 - In this example the ROC includes the unit circle, so DTFT exists
- Not all sequence have a z-transform
- Example: $x[n] = \cos(\omega_o n)$
 - Does not converge for any r
 - No ROC, No z-transform
 - But DTFT exists?!
 - Sequence has finite energy
 - DTFT converges in the mean-squared sense

Right-Sided Exponential Sequence Example

$$x[n] = a^{n}u[n] \implies X(z) = \sum_{n=-\infty}^{\infty} a^{n}u[n]z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^{n}$$

• For Convergence we require

$$\sum_{n=0}^{\infty} \left| a z^{-1} \right|^n < \infty$$

• Hence the ROC is defined as

$$\left|az^{-1}\right|^{n} < 1 \Longrightarrow \left|z\right| > \left|a\right|$$

• Inside the ROC series converges to

$$X(z) = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

• Geometric series formula

$$\sum_{n=N_1}^{N_2} a^n = \frac{a^{N_1} - a^{N_2 + 1}}{1 - a}$$



- Region outside the circle of radius a is the ROC
- Right-sided sequence ROCs extend outside a circle

Same Example Alternative Way

$$x[n] = a^{n}u[n] \implies X(z) = \sum_{n=-\infty}^{\infty} a^{n}u[n]z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^{n}$$
$$\sum_{n=N_{1}}^{N_{2}} \alpha^{n} = \frac{\alpha^{N_{1}} - \alpha^{N_{2}+1}}{1 - \alpha}$$
$$\sum_{n=0}^{\infty} (az^{-1})^{n} = \frac{(az^{-1})^{0} - (az^{-1})^{\infty}}{1 - az^{-1}} \qquad |z| > |a|$$

• For the term with infinite exponential to vanish we need

$$|az^{-1}| < 1 \implies |a| < |z|$$

- Determines the ROC (same as the previous approach)
- In the ROC the sum converges to

$$X(z) = \sum_{n=0}^{\infty} (az^{-1})^n = \frac{1}{1 - az^{-1}}$$

Two-Sided Exponential Sequence Example





Finite Length Sequence





Properties of The ROC of z-Transform

- The ROC is a ring or disk centered at the origin
- DTFT exists if and only if the ROC includes the unit circle
- The ROC cannot contain any poles
- The ROC for finite-length sequence is the entire z-plane
 - except possibly z = 0 and $z = \infty$
- The ROC for a right-handed sequence extends outward from the outermost pole possibly including $z = \infty$
- The ROC for a left-handed sequence extends inward from the innermost pole possibly including z = 0
- The ROC of a two-sided sequence is a ring bounded by poles
- The ROC must be a connected region
- A z-transform does not uniquely determine a sequence without specifying the ROC

Stability, Causality, and the ROC

- Consider a system with impulse response *h*[*n*]
- The z-transform H(z) and the pole-zero plot shown below
- Without any other information h[n] is not uniquely determined - |z| > 2 or $|z| < \frac{1}{2}$ or $\frac{1}{2} < |z| < 2$
- If system stable ROC must include unit-circle: $\frac{1}{2} < |z| < 2$
- If system is **causal** must be right sided: |z| > 2

